

**Exercise 1 - Numerical methods for fluid-structure interaction  
(Winter term 2015)**

**Exercise 1.1:** Find yourself examples where fluid-structure interaction takes place in daily life or academic problems. What are characteristic properties in your example?

**Exercise 1.2:** In many applications, the deformation and displacements are infinitesimal small and thus Lagrangian and Eulerian frameworks can be identified (based on a first order approximation). Thus there is no need to distinguish between different coordinate systems. Let us justify this point of view in this exercise. Given  $\|\nabla u\| \ll 1$ , derive the linearized expressions for the deformation gradient  $F$ , its determinant  $J$  and the strain  $E$ .

**Exercise 1.3:** The material time derivative of an Eulerian field is a key quantity in continuum mechanics and later in fluid-structure interaction modeling.

- Let  $f(t, x) : \mathbb{R}^m \rightarrow \mathbb{R}$  and  $x \in \mathbb{R}^{m-1}$ . Proof:

$$D_t f(t, x) = \partial_t f(t, x) + \nabla f(t, x) \cdot v(t, x),$$

where  $D_t$  denotes the total time derivative.

- Explain this formula in your own words.

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**Discussion of exercises: Oct 12, 2015**